

Statistical Mechanics and Thermodynamics

Résumé

Short Summary

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Winter term 2018/2019

Version: 7. November 2018

Chaos

Hamilton mechanics: trajectories cannot intersect in phase space. Hence a chaotic dynamics requires at least 3 degrees of freedom. Stationarity means time-independence (fixed points).

Fixed points of first-order differential equations:

$$\frac{d}{dt}y(t) = f(y) \quad \Rightarrow \quad f(y^*) = 0.$$

Stability of a fixed point of such a differential equation:

$$f'(y^*) > 0 \Leftrightarrow \text{unstable}, \quad f'(y^*) < 0 \Leftrightarrow \text{stable}$$

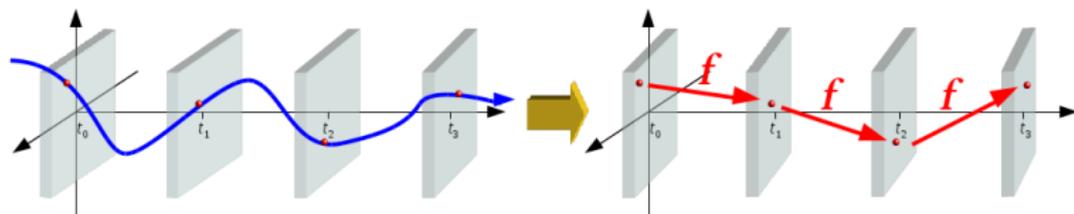
There are several types of solutions:

- ▶ **Stationary** solutions (fixed points)
- ▶ **Periodic** solutions (system returns to initial state)
- ▶ **Chaotic** solutions (system never returns to the initial state)

One goes from periodic to chaotic behavior by **period doubling**.

Iterative maps

Poincaré sections motivate the study of **iterative maps**:



Iterative map:

$$x_{n+1} = g(x_n)$$

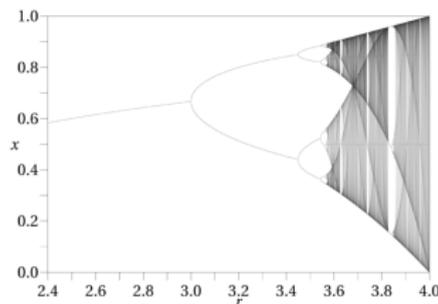
Ordinary fixed point:

$$x^* = g(x^*)$$

Stability condition:

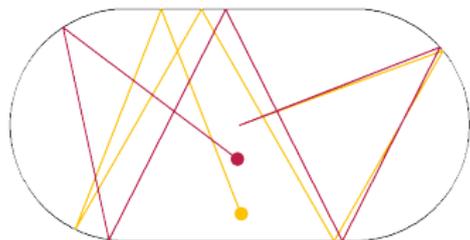
$$|g'(x^*)| < 1$$

Bifurcations: When a fixed point $x^* = g(x^*)$ becomes unstable, it may split up into two new branches (period doubling) given by $x^* = g(g(x^*))$, $x^* = g(g(g(x^*)))$,

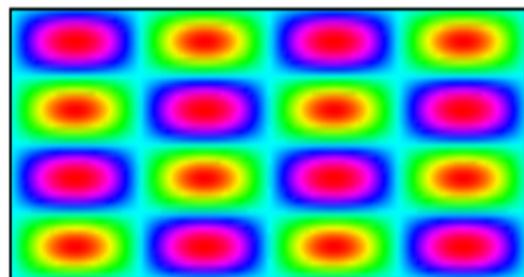


Classical and quantum billiards

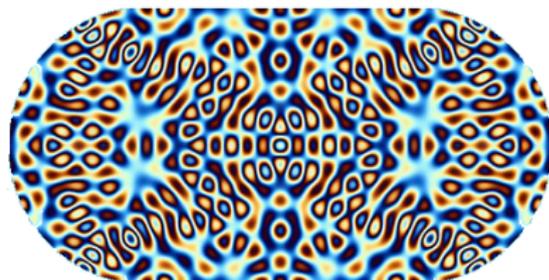
Stadium billiard: The round edges of a stadium billiard magnify small changes in the initial condition, leading to a chaotic behavior.



Quantum-mechanical wave functions:



non-chaotic



chaotic

Most complex systems in Nature are chaotic!

Time reversal symmetry

In **classical mechanics**, the Hamilton equations

$$\frac{d}{dt}q = \frac{\partial H}{\partial p}, \quad \frac{d}{dt}p = -\frac{\partial H}{\partial q}$$

is invariant under $p \rightarrow -p, t \rightarrow -t$, meaning that it can run backward in time. It has a **time-reversal symmetry**.

In **quantum mechanics**, the Schrödinger equation

$$i\hbar \frac{d}{dt}|\psi(t)\rangle = \mathbf{H}|\psi(t)\rangle \quad \Rightarrow \quad |\psi(t)\rangle = e^{-\frac{i}{\hbar}\mathbf{H}t}|\psi(0)\rangle$$

is invariant under $\mathbf{H} \rightarrow -\mathbf{H}, t \rightarrow -t$, hence it can also run backward in time. Thus it is also symmetric under time-reversal.

Randomness is by definition *not* invariant under time reversal. The quantum-mechanical measurement process is in fact random and cannot be reversed.

Probability

- ▶ **Objective (frequentist) interpretation:** Probability is a property of a system, given by the relative frequency in the limit of infinitely many stochastically independent experiments.
 - ▶ **Subjective interpretation:** Probability reflects a subjective believe of a likelihood. Different persons may describe the same situation with different probabilities.
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Definitions:

- ▶ The **outcome** or result of an experiment, and likewise the microstate of a physical system, is denoted by $\omega \in \Omega$.
- ▶ The **sample space** Ω is the set of all possible outcomes.
- ▶ An **event** A, B, C, \dots is defined as a subset of Ω
- ▶ The **event space** Σ is the set of all events, the power set of Ω .

Axiomatic definition of probability

Kolmogorov Axioms:

A function $P : \Sigma \rightarrow \mathbb{R}$ is called a **probability measure**, if

K1: P is a probability-valued, i.e. $\forall A \in \Sigma : P(A) \in [0, 1]$

K2: The certain event Ω occurs with prob. $P(\Omega) = 1$.

K3: P is additive on non-overlapping events, that is, for a set of events $\{A_1, A_2, \dots\}$ which cannot happen simultaneously ($A_i \cap A_j = \emptyset$) we have

$$P\left[\bigcup_i A_i\right] = \sum_i P(A_i).$$

The triple (Ω, Σ, P) , i.e., the sample space Ω together with its own power set Σ and a probability measure P , which obeys the three axioms of Kolmogorov listed above, is called **probability space**.

Conditional probabilities

$P(A|B)$ is the probability of A under the condition that B is true. It is defined by

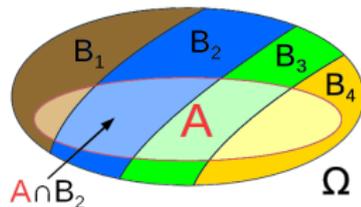
$$P(A|B) = \frac{P(A \cap B)}{P(B)}$$

The vertical dash “|” is read as “conditioned on” or “given that”.

Law of total probability:

($\{B_j\}$ = segmentation of Ω):

$$P(A) = \sum_j P(A|B_j) P(B_j)$$



Bayes theorem:

Important in economics, relates $P(A|B)$ and $P(B|A)$:

$$P(A|B) = \frac{P(A)}{P(B)} P(B|A)$$

Statistical independence

Two events A, B are called **statistically independent** if mutual conditioning does not have any effect, i.e.

$$P(A|B) = P(A), \quad P(B|A) = P(B).$$

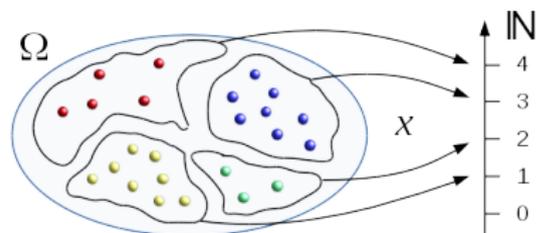
This implies that two events are statistically independent if and only if the intersection event **factorizes**:

$$P(A \cap B) = P(A)P(B)$$

Functions on state spaces

Random variables:

A random variable X maps the elements of the sample space onto numbers ($\mathbb{N}, \mathbb{Z}, \mathbb{C}, \mathbb{R}$), z.B.:



$$X : \Omega \mapsto \mathbb{R} : \omega \mapsto x$$

This map induces a **probability distribution** of X , namely, the probability $P(x) = P_X(x)$ that X gives the result x is defined by

$$P_X(x) = \sum_{\omega \in X^{-1}(x)} P_\omega.$$

Average:

The arithmetic average of X tends to the **expectation value**:

$$\langle x \rangle = \mathbb{E}(X) := \sum_{x \in X(\Omega)} x P(x)$$

Moments

Each discrete probability distribution is characterized by certain (non-central) **moments**:

$$m_n = \mathbb{E}(X^n) = \langle x^n \rangle. \quad (n = 0, 1, 2, \dots)$$

Important statistical quantities are:

- ▶ $m_0 = 1$ Normalization
- ▶ m_1 Expectation value
- ▶ $\sigma^2 = m_2 - m_1^2$ Variance

Because of the subtraction of m_1^2 in the variance, some people like to define the so-called **central moments**:

$$\mu_n := \mathbb{E}\left(\left(X - \mathbb{E}(X)\right)^n\right) = \langle (x - \langle x \rangle)^n \rangle.$$

Then the variance is simply given by $\sigma^2 = \mu_2$.

Chapter 2: Information Entropy

Information Entropy

What is information?

- ▶ Information reduces the ignorance about an object.
- ▶ Information is measured in the unit of *bit*.
- ▶ The information of an object is the minimal number of *bits* that is needed to fully characterize its state or condition.

Entropy and Information are synonymous.

The main properties of information

- ▶ **Contextuality**: Information depends on the context of the description.
- ▶ **Additivity**: The information of uncorrelated systems is the sum of the information of its parts.
- ▶ **Relativity**: Information describes the relation between object and observer. Previous knowledge reduces the information.

Information without previous knowledge

Without previous knowledge, the entropy (information) of an object is given by

$$H = \log_2 |\Omega|$$

- ▶ H is the number of bits needed to identify an object of Ω .
- ▶ Information can be non-integer if $|\Omega|$ is not a power of 2.
- ▶ The **context** is defined by the choice of Ω .
- ▶ The **additivity** is ensured by the logarithm:

$$|\Omega| = |\Omega_1| \cdot |\Omega_2| \quad \Rightarrow \quad H = H_1 + H_2.$$

- ▶ The aspect of **relativity** enters by specifying that the observer has no previous knowledge.

Definition of Information in various disciplines

The definition of entropy/information differs in various fields:

Information technology: $H = \log_2 |\Omega|$

Mathematics: $H = \ln |\Omega|$

Physics: $S = k_B \ln |\Omega|$

The most obscure definition is used in Physics, where we use the letter S and assign the unit [*Joule/Kelvin*] by multiplying the logarithm with the Boltzmann constant

$$k_B \simeq 1.38065 \cdot 10^{-23} \text{ J/K}.$$

This is a historical accident.

- ▶ **All these definitions differ only by a prefactor.**
- ▶ **In this course we will mainly use the second definition.**

Information with previous knowledge

- Previous knowledge is encoded in a **probability distribution** P_ω .
- Here each configuration $\omega \in \Omega$ carries an **individual entropy**:

Individual entropy: $H_\omega = -\log_2 P_\omega$

- This allows us to compute the **average entropy**:

Average entropy: $H = \langle H \rangle = -\sum_{\omega \in \Omega} P_\omega \log_2 P_\omega$

This is the Shannon-Gibbs-Boltzmann entropy/information.

- From now on we will use the **natural logarithm** instead of \log_2 .

Properties of the Shannon entropy

- ▶ By Jensens inequality we can prove that the mean entropy is bounded from above by

$$H \leq \ln |\Omega|$$